Supporting Information for

Local pressure for inhomogeneous fluids

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S.1. CONSERVATION OF NUMBER AND MOMENTUM DENSITIES

The dynamics of operators is defined by

$$\partial_t X(t) = i \left[\mathcal{H}_N(t), X(t) \right], \tag{S.1}$$

with the Hamiltonian given by

$$\mathcal{H}_{N}(t) = H_{N}(t) + \sum_{\alpha=1}^{N} v^{\text{ext}}(\mathbf{q}_{\alpha}(t), t), \tag{S.2}$$

$$H_{N}(t) = \sum_{\alpha=1}^{N} \frac{p_{\alpha}^{2}(t)}{2m} + \frac{1}{2} \sum_{\alpha \neq \sigma=1}^{N} U_{N}(|\mathbf{q}_{\alpha}(t) - \mathbf{q}_{\sigma}(t)|). \tag{S.3}$$

The operators corresponding to the number and momentum densities are

$$n(\mathbf{r},t) = \sum_{\alpha=1}^{N} \delta(\mathbf{r} - \mathbf{q}_{\alpha}(t)), \quad \mathbf{p}(\mathbf{r},t) = \sum_{\alpha=1}^{N} \frac{1}{2} \left[\mathbf{p}_{\alpha}(t), \delta(\mathbf{r} - \mathbf{q}_{\alpha}(t)) \right]_{+}.$$
 (S.4)

The brackets $[A, B]_{+}$ with a subscript + denote an anti-commutator.

Local conservation laws follow exactly from this Hamiltonian dynamics¹. The simplest is the conservation of number density

$$\partial_{t} n\left(\mathbf{r},t\right) = i\left[\mathcal{H}_{N}\left(t\right), n\left(\mathbf{r},t\right)\right] = \sum_{\alpha=1}^{N} i\left[\frac{p_{\alpha}^{2}\left(t\right)}{2m}, \delta\left(\mathbf{r} - \mathbf{q}_{\alpha}\left(t\right)\right)\right]$$

$$= \sum_{\alpha=1}^{N} i\left\{\frac{p_{\alpha j}\left(t\right)}{2m}\left[p_{\alpha j}\left(t\right), \delta\left(\mathbf{r} - \mathbf{q}_{\alpha}\left(t\right)\right)\right] + \left[p_{\alpha j}\left(t\right), \delta\left(\mathbf{r} - \mathbf{q}_{\alpha}\left(t\right)\right)\right]\frac{p_{\alpha j}\left(t\right)}{2m}\right\}$$

$$= \frac{1}{2m}\sum_{\alpha=1}^{N} \left\{p_{\alpha j}\left(t\right)\partial_{q_{\alpha j}\left(t\right)}\delta\left(\mathbf{r} - \mathbf{q}_{\alpha}\left(t\right)\right) + \partial_{q_{\alpha j}\left(t\right)}\delta\left(\mathbf{r} - \mathbf{q}_{\alpha}\left(t\right)\right)p_{\alpha j}\left(t\right)\right\}$$
(S.5)

or, with the definition of $\mathbf{p}(\mathbf{r})$ in (S.4), the microscopic continuity equation is obtained

$$\partial_t n(\mathbf{r},t) + \frac{1}{m} \nabla \cdot \mathbf{p}(\mathbf{r},t) = 0.$$
 (S.6)

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Use has been made of the property

$$i\left[p_{\alpha i}\left(t\right), A\left(\mathbf{q}_{\alpha}\left(t\right)\right)\right] = \partial_{q_{\alpha i}\left(t\right)} A\left(\mathbf{q}_{\alpha}\left(t\right)\right). \tag{S.7}$$

The time derivative of $\mathbf{p}(\mathbf{r},t)$ follows in a similar way

$$\begin{split} \partial_{t}p_{j}\left(\mathbf{r},t\right) &= \frac{1}{2}\sum_{\alpha=1}^{N}\left\{\left[p_{\alpha j}\left(t\right),i\left[\mathcal{H}_{N}\left(t\right),\delta\left(\mathbf{r}-\mathbf{q}_{\alpha}\left(t\right)\right)\right]\right]_{+} + \left[i\left[\mathcal{H}_{N}\left(t\right),p_{\alpha j}\left(t\right)\right],\delta\left(\mathbf{r}-\mathbf{q}_{\alpha}\left(t\right)\right)\right]_{+}\right\} \\ &= \frac{1}{2}\sum_{\alpha=1}^{N}\left\{\left[p_{\alpha j}\left(t\right),i\left[\frac{p_{\alpha}^{2}\left(t\right)}{2m},\delta\left(\mathbf{r}-\mathbf{q}_{\alpha}\left(t\right)\right)\right]\right]_{+} + \left[i\left[\mathcal{H}_{N}\left(t\right),p_{\alpha j}\left(t\right)\right],\delta\left(\mathbf{r}-\mathbf{q}_{\alpha}\left(t\right)\right)\right]_{+}\right\} \\ &= \frac{1}{4m}\sum_{\alpha=1}^{N}\left[p_{\alpha j}\left(t\right),\left[p_{\alpha k}\left(t\right),\partial_{q_{\alpha k}\left(t\right)}\Delta\left(\mathbf{r}-\mathbf{q}_{\alpha}\left(t\right)\right)\right]_{+}\right]_{+} - \frac{1}{2}\sum_{\alpha=1}^{N}\delta\left(\mathbf{r}-\mathbf{q}_{\alpha}\left(t\right)\right)\partial_{q_{\alpha j}\left(t\right)}v^{\mathrm{ext}}(\mathbf{q}_{\alpha}\left(t\right),t\right) \\ &- \frac{1}{4}\sum_{\alpha=1}^{N}\sum_{\beta=1}^{N}\left[\delta\left(\mathbf{r}-\mathbf{q}_{\alpha}\left(t\right)\right),\partial_{q_{\alpha j}\left(t\right)}V\left(|\mathbf{q}_{\beta}\left(t\right)-\mathbf{q}_{\sigma}\left(t\right)|\right)\right]_{+} \end{split}$$

$$= -\partial_{r_{k}} \frac{1}{4m} \sum_{\alpha=1}^{N} \left[p_{\alpha j}(t), \left[p_{\alpha k}(t), \delta\left(\mathbf{r} - \mathbf{q}_{\alpha}(t)\right) \right]_{+} \right]_{+} + \frac{1}{2} \sum_{\alpha=1}^{N} \delta\left(\mathbf{r} - \mathbf{q}_{\alpha}(t)\right) F_{\alpha j}^{\text{ext}}(\mathbf{q}_{\alpha}(t))$$

$$+ \frac{1}{2} \sum_{\alpha=1}^{N} \sum_{\beta=1}^{N} F_{\alpha \beta j}(\left|\mathbf{q}_{\alpha}(t) - \mathbf{q}_{\beta}(t)\right|) \delta\left(\mathbf{r} - \mathbf{q}_{\alpha}(t)\right)$$
(S.8)

where $F_{\alpha\beta j}\left(\left|\mathbf{q}_{\alpha}\left(t\right)-\mathbf{q}_{\beta}\left(t\right)\right|\right)$ is the j^{th} component of the force on particle α due to particle β

$$F_{\alpha\beta j}\left(\left|\mathbf{q}_{\alpha}-\mathbf{q}_{\beta}\right|\right) = -\partial_{q_{\alpha j}(t)}V\left(\left|\mathbf{q}_{\alpha}\left(t\right)-\mathbf{q}_{\beta}\left(t\right)\right|\right),\tag{S.9}$$

and $F_{\alpha j}^{\mathrm{ext}}\left(\mathbf{q}_{\alpha}\left(t\right)\right)$ is the j^{th} component of the force on particle α due to the external potential

$$F_{\alpha j}^{\text{ext}}\left(\mathbf{q}_{j}\right)=-\partial_{q_{\alpha j}\left(t\right)}u\left(\mathbf{q}_{\alpha}\left(t\right),t\right). \tag{S.10}$$

The last term on the right side of (S.8) can be rewritten as

$$\sum_{\alpha \neq \beta=1}^{N} F_{\alpha\beta j} (|\mathbf{q}_{\alpha}(t) - \mathbf{q}_{\beta}(t)|) \delta (\mathbf{r} - \mathbf{q}_{\alpha}(t)) = \sum_{\alpha \neq \beta=1}^{N} F_{\beta\alpha j} (|\mathbf{q}_{\beta}(t) - \mathbf{q}_{\alpha}(t)|) \delta (\mathbf{r} - \mathbf{q}_{\beta}(t))$$

$$= -\sum_{\alpha \neq \beta=1}^{N} F_{\alpha\beta j} (|\mathbf{q}_{\alpha}(t) - \mathbf{q}_{\beta}(t)|) \delta (\mathbf{r} - \mathbf{q}_{\beta}(t)) \tag{S.11}$$

as follows from Newton's third law. Therefore

$$\sum_{\alpha \neq \beta=1}^{N} F_{\alpha\beta j} (|\mathbf{q}_{\alpha}(t) - \mathbf{q}_{\beta}(t)|) \delta(\mathbf{r} - \mathbf{q}_{\alpha}(t)) = \frac{1}{2} \sum_{\alpha \neq \beta=1}^{N} F_{\alpha\beta j} (|\mathbf{q}_{\alpha}(t) - \mathbf{q}_{\beta}(t)|) \times (\delta(\mathbf{r} - \mathbf{q}_{\alpha}(t)) - \delta(\mathbf{r} - \mathbf{q}_{\beta}(t))).$$
(S.12)

Next note the identity

$$\delta\left(\mathbf{r} - \mathbf{q}_{1}\right) - \delta\left(\mathbf{r} - \mathbf{q}_{2}\right) = \int_{\lambda_{2}}^{\lambda_{1}} d\lambda \frac{d}{d\lambda} \delta\left(\mathbf{r} - \mathbf{x}\left(\lambda\right)\right), \quad \mathbf{x}\left(\lambda_{1}\right) = \mathbf{q}_{1}, \quad \mathbf{x}\left(\lambda_{2}\right) = \mathbf{q}_{2}. \tag{S.13}$$

Here $\mathbf{x}(\lambda)$ is an arbitrary path for the vector \mathbf{x} moving from $\mathbf{x}(\lambda_2) = \mathbf{q}_2$ to $\mathbf{x}(\lambda_1) = \mathbf{q}_1$. Carrying out the derivative gives

$$\delta(\mathbf{r} - \mathbf{q}_1) - \delta(\mathbf{r} - \mathbf{q}_2) = -\partial_{r_k} \mathcal{D}_k(\mathbf{r}, \mathbf{q}_1, \mathbf{q}_2), \tag{S.14}$$

where

$$\mathcal{D}_{k}\left(\mathbf{r}, \mathbf{q}_{1}, \mathbf{q}_{2}\right) = \int_{\lambda_{2}}^{\lambda_{1}} d\lambda \frac{dx_{k}\left(\lambda\right)}{d\lambda} \delta\left(\mathbf{r} - \mathbf{x}\left(\lambda\right)\right). \tag{S.15}$$

Use of (S.14) in (S.12) and (S.8) gives the momentum conservation law

$$\partial_t p_j(\mathbf{r}, t) + \partial_{r_k} t_{jk}(\mathbf{r}, t) = f_j(\mathbf{r}, t)$$
 (S.16)

where the total momentum flux $t_{\alpha\beta}(\mathbf{r},t)$ is the sum of a kinetic and potential part

$$t_{\alpha\beta}(\mathbf{r},t) = t_{\alpha\beta}^{K}(\mathbf{r},t) + t_{\alpha\beta}^{P}(\mathbf{r},t), \qquad (S.17)$$

$$t_{jk}^{K}(\mathbf{r},t) = \frac{1}{4m} \sum_{\alpha=1}^{N} \left[p_{\alpha j}(t), \left[p_{\alpha k}(t), \delta\left(\mathbf{r} - \mathbf{q}_{\alpha}(t)\right) \right]_{+} \right]_{+}, \tag{S.18}$$

$$t_{jk}^{P}(\mathbf{r},t) = \frac{1}{4} \sum_{\alpha \neq \beta=1}^{N} F_{\alpha\beta j}(|\mathbf{q}_{\alpha}(t) - \mathbf{q}_{\beta}(t)|) \mathcal{D}_{k}(\mathbf{r}, \mathbf{q}_{\alpha}(t), \mathbf{q}_{\beta}(t)).$$
(S.19)

The right side of (S.16) is the force density of the external potential

$$f_{j}(\mathbf{r},t) = \sum_{\alpha=1}^{N} \delta\left(\mathbf{r} - \mathbf{q}_{j}(t)\right) F_{\alpha j}^{\text{ext}}(\mathbf{q}_{\alpha}(t)). \tag{S.20}$$

S.2. DETERMINATION OF MOMENTUM FLUX

The straightforward derivation of the momentum conservation law in Appendix S.1 leads to a momentum flux (as in the text the dependence on t will be left implicit as it plays no role in the following)

$$t_{ij}(\mathbf{r}) = \frac{1}{4m} \sum_{\alpha=1}^{N} \left[p_{i\alpha}, \left[p_{j\alpha}, \delta \left(\mathbf{r} - \mathbf{q}_{\alpha} \right) \right]_{+} \right]_{+}$$
$$+ \frac{1}{2} \sum_{\alpha \neq \sigma=1}^{N} F_{\alpha\sigma i} \left(\left| \mathbf{q}_{\alpha} - \mathbf{q}_{\sigma} \right| \right) \mathcal{D}_{j} \left(\mathbf{r}, \mathbf{q}_{\alpha}, \mathbf{q}_{\sigma} \right), \tag{S.21}$$

where the operator $\mathcal{D}_{j}\left(\mathbf{r},\mathbf{q}_{\alpha},\mathbf{q}_{\sigma}\right)$ is given by

$$\mathcal{D}_{j}\left(\mathbf{r},\mathbf{q}_{1},\mathbf{q}_{2}\right) \equiv \int_{\mathcal{C}} d\lambda \frac{dx_{j}\left(\lambda\right)}{d\lambda} \delta\left(\mathbf{r} - \mathbf{x}\left(\lambda\right)\right), \quad \mathbf{x}\left(\lambda_{1}\right) = \mathbf{q}_{1}, \quad \mathbf{x}\left(\lambda_{2}\right) = \mathbf{q}_{2}.$$
 (S.22)

Here C is an arbitrary continuous path connecting $\mathbf{x}(\lambda)$ between λ_1 and λ_2 . Consider the simplest choice a linear path

$$\mathbf{x}(\lambda) = \mathbf{q}_1 + (\mathbf{q}_2 - \mathbf{q}_1)\lambda. \tag{S.23}$$

Then

$$\mathcal{D}_{j}\left(\mathbf{r},\mathbf{q}_{1},\mathbf{q}_{2}\right) \rightarrow \left(q_{2j}-q_{1j}\right) \int_{0}^{1} d\lambda \delta\left(\mathbf{r}-\mathbf{q}_{1}-(\mathbf{q}_{2}-\mathbf{q}_{1})\lambda\right), \quad \mathbf{x}\left(\lambda_{1}\right) = \mathbf{q}_{1}, \quad \mathbf{x}\left(\lambda_{2}\right) = \mathbf{q}_{2}. \quad (S.24)$$

Since $F_{\alpha\sigma i}(|\mathbf{q}_{\alpha}-\mathbf{q}_{\sigma}|) \propto (q_{2i}-q_{1i})$ use of (S.24) in (S.21) leads to a form for the momentum flux that is symmetric, $t_{ij}(\mathbf{r}) = t_{ji}(\mathbf{r})$, and consequently its divergence with respect to first and second indices are the same

$$\partial_j t_{ij}(\mathbf{r}) = \partial_j t_{ji}(\mathbf{r}).$$
 (S.25)

Next define another symmetric momentum flux whose divergences are the same as those of (S.25)

$$t'_{ij}(\mathbf{r}) = t_{ij}(\mathbf{r}) + \epsilon_{ik\ell}\epsilon_{jmn}\partial_k\partial_m A_{\ell n}(\mathbf{r}), \qquad (S.26)$$

for some unspecified tensor field $A_{\ell n}(\mathbf{r})$ and $\epsilon_{ik\ell}$ is the Levi-Cevita tensor. This added term is seen to be the curl of a vector associated with each component of $t_{ij}(\mathbf{r})$ (i.e., noting that $t_{ij}(\mathbf{r})$ transforms as vector for components i at fixed j, and vice versa). With the additional condition $A_{\ell n}(\mathbf{r}) = A_{n\ell}(\mathbf{r})$, it is verified that

$$t'_{ii}(\mathbf{r}) = t'_{ii}(\mathbf{r}) , \qquad (S.27)$$

$$\partial_j t'_{ij}(\mathbf{r}) = \partial_j t'_{ji}(\mathbf{r}). \tag{S.28}$$

The two indefinite features of the momentum flux have now been made explicit with the contour fixed by symmetry and the choice of a term with vanishing divergence. It is interesting to note that the contribution from different contours, denoted by $\Delta \mathcal{D}_j$ ($\mathbf{r}, \mathbf{q}_1, \mathbf{q}_2$) has a vanishing divergence, since the endpoints of the integration in (S.24) are the same for all contours. Consequently, the divergence of $\Delta \mathcal{D}_j$ vanishes, $\partial_j \Delta \mathcal{D}_j = 0$. It follows that $\Delta \mathcal{D}_j$ is the curl of some vector. Hence, the difference between contours is included in the form (S.26).

S.3. PERCUS PRESSURE TENSOR

The free energy is obtained from the grand potential by a Legendre transform

$$\beta F(\beta, V \mid \overline{n}) = -Q^{e}(\beta, V \mid \nu) + \int d\mathbf{r} \overline{n}(\mathbf{r}) \nu(\mathbf{r})$$
(S.29)

where $\overline{n}(\mathbf{r}) = \langle n(\mathbf{r}) \rangle$ is the average number density. The free energy and grand potential are expressed as integrals of their respective densities

$$F(\beta, V \mid \overline{n}) = \int d\mathbf{r} f(\mathbf{r}, \beta \mid \overline{n}), \quad Q^{e}(\beta, V \mid \nu) = \int d\mathbf{r} \beta p_{T}(\mathbf{r}, \beta \mid \nu)$$
(S.30)

so that

$$\beta p_T(\mathbf{r}, \beta \mid \nu) = \overline{n}(\mathbf{r}) \nu(\mathbf{r}) - f(\mathbf{r}, \beta \mid \overline{n}). \tag{S.31}$$

The Percus pressure tensor² is defined by

$$p_{ij}(\mathbf{r},\beta \mid \overline{n}) \equiv \delta_{ij} p_T(\mathbf{r},\beta \mid \nu) + \int d\mathbf{r}' r_i' \int_0^1 d\gamma \frac{\delta f(\mathbf{r} + \gamma \mathbf{r}' - \mathbf{r}',\beta \mid \overline{n})}{\delta \overline{n}(\mathbf{r} + \gamma \mathbf{r}')} \partial_j \overline{n}(\mathbf{r} + \gamma \mathbf{r}').$$
 (S.32)

The corresponding mechanical pressure is

$$p_{m}\left(\mathbf{r},\beta\mid\overline{n}\right) = p_{T}\left(\mathbf{r},\beta\mid\nu\right) + \frac{1}{3}\int d\mathbf{r}' \int_{0}^{1} d\gamma \frac{\delta f\left(\mathbf{r}+\gamma\mathbf{r}'-\mathbf{r}',\beta\mid\overline{n}\right)}{\delta\overline{n}\left(\mathbf{r}+\gamma\mathbf{r}'\right)} r'_{i}\partial_{i}\overline{n}\left(\mathbf{r}+\gamma\mathbf{r}'\right). \tag{S.33}$$

No motivation nor interpretation for this result is provided.

First, prove the force balance equation. Separate the pressure tensor into two parts

$$p_{ij}(\mathbf{r},\beta \mid \overline{n}) = \delta_{ij}p_T(\mathbf{r},\beta \mid \overline{n}) + \Delta P_{ij}(\mathbf{r},\beta \mid \overline{n}), \qquad (S.34)$$

$$\Delta P_{ij}\left(\mathbf{r},\beta\mid\overline{n}\right) = \int d\mathbf{r}' r_i' \int_0^1 d\gamma \frac{\delta f\left(\mathbf{r} + \gamma \mathbf{r}' - \mathbf{r}',\beta\mid\overline{n}\right)}{\delta \overline{n} (\mathbf{r} + \gamma \mathbf{r}')} \partial_j \overline{n} \left(\mathbf{r} + \gamma \mathbf{r}'\right).$$

Then

$$\delta_{ij}\partial_{i}\beta p_{T}\left(\mathbf{r},\beta\mid\overline{n}\right) = \delta_{ij}\partial_{i}\left(\overline{n}(\mathbf{r})\nu(\mathbf{r}) - \beta f\left(\mathbf{r},\beta\mid\overline{n}\right)\right)$$

$$= \overline{n}(\mathbf{r})\partial_{i}\nu(\mathbf{r}) + \nu(\mathbf{r})\partial_{i}\overline{n}(\mathbf{r}) - \partial_{i}\beta f\left(\mathbf{r},\beta\mid\overline{n}\right)$$
(S.35)

and

$$\partial_{i}\beta\Delta p_{ij}\left(\mathbf{r},\beta\mid\overline{n}\right) = \int d\mathbf{r}'r'_{i}\partial_{i}\int_{0}^{1}d\gamma\frac{\delta\beta f\left(\mathbf{r}+\gamma\mathbf{r}'-\mathbf{r}',\beta\mid\overline{n}\right)}{\delta\overline{n}(\mathbf{r}+\gamma\mathbf{r}')}\partial_{j}\overline{n}\left(\mathbf{r}+\gamma\mathbf{r}'\right)$$

$$= \int d\mathbf{r}'\int_{0}^{1}d\gamma\partial_{\gamma}\left(\frac{\delta\beta f\left(\mathbf{r}+\gamma\mathbf{r}'-\mathbf{r}',\beta\mid\overline{n}\right)}{\delta\overline{n}(\mathbf{r}+\gamma\mathbf{r}')}\partial_{j}\overline{n}\left(\mathbf{r}+\gamma\mathbf{r}'\right)\right)$$

$$= \int d\mathbf{r}'\left(\frac{\delta\beta f\left(\mathbf{r},\beta\mid\overline{n}\right)}{\delta\overline{n}(\mathbf{r}+\mathbf{r}')}\partial_{j}\overline{n}\left(\mathbf{r}+\mathbf{r}'\right) - \frac{\delta\beta f\left(\mathbf{r}-\mathbf{r}',\beta\mid\overline{n}\right)}{\delta\overline{n}(\mathbf{r})}\partial_{j}\overline{n}\left(\mathbf{r}\right)\right)$$

$$= \int d\mathbf{r}_{1}\frac{\delta\beta f\left(\mathbf{r},\beta\mid\overline{n}\right)}{\delta\overline{n}(\mathbf{r}_{1})}\partial_{1j}\overline{n}\left(\mathbf{r}_{1}\right) - \frac{\delta\beta F\left(\beta\mid\overline{n}\right)}{\delta\overline{n}(\mathbf{r})}\partial_{j}\overline{n}\left(\mathbf{r}\right)$$

$$= -\left(\nu(\mathbf{r})\partial_{j}\overline{n}\left(\mathbf{r}\right) - \partial_{j}\beta f\left(\mathbf{r},\beta\mid\overline{n}\right)\right) \tag{S.36}$$

so the force balance equation is verified

$$\partial_i \beta p_{ij} (\mathbf{r}, \beta \mid \overline{n}) = \overline{n}(\mathbf{r}) \partial_j \nu(\mathbf{r}).$$
 (S.37)

For the pressure to qualify as a thermodynamic pressure it should satisfy

$$\int d\mathbf{r}\beta p_m(\mathbf{r},\beta \mid \nu) = Q^e(\beta, V \mid \nu). \tag{S.38}$$

Use of the Percus form (S.33) gives this condition to be

$$\int d\mathbf{r} \frac{1}{3} \int d\mathbf{r}' \int_0^1 d\gamma \frac{\delta f(\mathbf{r} + \gamma \mathbf{r}' - \mathbf{r}', \beta \mid \overline{n})}{\delta \overline{n}(\mathbf{r} + \gamma \mathbf{r}')} r_i' \partial_i \overline{n}(\mathbf{r} + \gamma \mathbf{r}') = 0.$$
 (S.39)

The Appendix of Ref. 3 claims that this is true, but no proof is given.

^[1] Dufty JW, Luo K, Wrighton JM. Generalized hydrodynamics revisited. Phys Rev Research. 2020;2:023036.

^[2] Percus JK. The pressure tensor in a non-uniform fluid. Chem Phys Lett. 1986;123:311-314.

^[3] Pozhar LA. Transport theory of inhomogeneous fluids. World Scientific, 1994.